

Robot End-Of-Arm Tool

Our EOAT , also called tool changers or quick changers, allow end-of-arm tooling or end effectors to be quickly and accurately mounted to a robot arm. Quick Changers have two separate sides. One side is attached to the robot arm—the other side to the EOAT.

The EOAT mounts to the robot by connecting the two sides together. Our end of arm tooling (EOAT), grippers and robotic end effectors are custom designed and built for your specific application for increased speed and accuracy. Their robustly engineered construction and use of high quality components ensures long life and low maintenance.

HAI's end of arm tooling (EOAT), grippers and end effectors are compatible with most any robot, including 3-Axis, 6-Axis, SCARA and Side Entry robots. It provides the complete custom automated cell.



Uses:

Use Robotic Automation
End Of Arm Tooling (EOAT) for:

- Accurate Placement
- Cycle Consistency
- Mold Protection
- Improved Part Quality
- Reduced Maintenance Time
- Added Versatility

www.halinc.com • sales@halinc.com

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Contact:

US Office/ Headquarters
1688 Sierra Madre Circle,
Placentia, CA 92870

Phone: 877-411-8971
Fax: 877-411-8778

European Office
Horackova 1212/19, 140 00
Praha 4, Czech Republic

Phone: +420-241 402 417
Fax: +420-241 402 417

